

Model Test of Yield Acceleration Factor — K_c — of a Foundation Near Down-Hill Slope Induced Dynamic Waves

by

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Abstract

The finite element method is a powerful method to approximate the deformation of an element in a structure. Finite element analysis is also used to evaluate the safety of the structure. It is, however, far more difficult to model the progressive failure of soil structures. The conventional pseudo-static approach is used to simplify the computation of the upper limit of a slope under seismic load but does not yield information about the sliding displacement as such. In this paper, a technique based on the upper limit⁽¹⁾ is used to find the yield acceleration factor (K_c)⁽²⁾ of a foundation near a down-hill slope. Some assumptions are made. First, a logarithmic spiral rupture is assumed to start at an edge of the loaded area far from the slope. A landslide is assumed to behave as a rigid body so that the inertia force acts at its center of gravity. A final assumption is that the rate of kinematic energy of the landslide together with the load should be equal to the dissipation of the internal energy rate along the sliding line. Also in this paper, several effects of the model tests for slope collapses induced dynamic waves is described (Fig. 1). This experimental investigation is conducted to study seismic yield acceleration factor.

1. REVIEW OF THEORETICAL FORMULATION

By equating the rate of internal energy dissipation to the total rates of external work⁽¹⁾, we have

$$K = \frac{cF_c - \gamma r_0(F_1 - F_2 - F_3) - pF_p}{\gamma r_0(F_4 - F_5 - F_6) + xPF_q} \quad (1)$$

Herein,

$$F_1 = \frac{1}{3(1+9\tan^2\phi)} \{ \exp[3(\theta_h - \theta_0)\tan\phi] (3\tan\phi\cos\theta_h + \sin\theta_h) - 3\tan\phi\cos\theta_0 - \sin\theta_0 \}$$

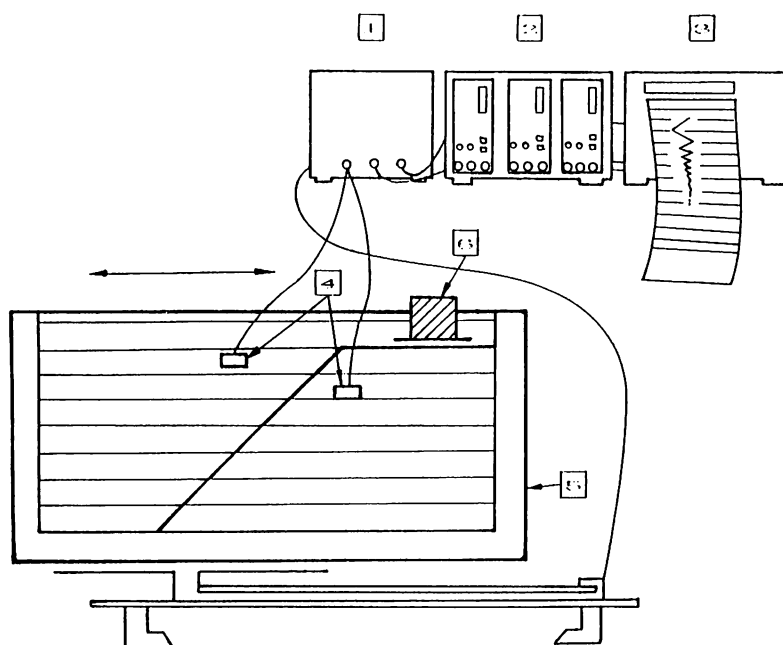
$$F_2 = \frac{1}{6} \frac{L}{r_0} 2\cos\theta_0 \cdot \sin\theta_0$$

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- [1] Shaking Table
- [2] Dynamic Strain Meter (DPM-6BA)
- [3] Rapicorder (RMV-30A)
- [4] Accelerometer (SHINKOH BAL-50G)
- [5] Acrylic Box (40 cm × 40 cm × 80 cm)
- [6] Surcharge Load

Fig. 1 Apparatuses of model test

$$F_3 = \frac{1}{6} \exp[(\theta_h - \theta_0) \tan \phi] \left\{ \sin(\theta_h - \theta_0) - \frac{L}{r_0} \sin \theta_h \right\} \cdot \{ \cos \theta_0 + \cos \theta_h \exp[(\theta_h - \theta_0) \tan \phi] \}$$

$$F_4 = \frac{1}{3(1+9 \tan^2 \phi)} \{ 3 \tan \phi \sin \theta_h - \cos \theta_h \} \exp[3(\theta_h - \theta_0) \tan \phi] \\ - 3 \tan \phi \sin \theta_0 + \cos \theta_0 \}$$

$$F_5 = \frac{1}{6} 2 \frac{L}{r_0} \sin^2 \theta_0 \quad F_p = \frac{L}{r_0} \cos \theta_0 \quad F_q = \frac{L}{r_0} \sin \theta_0$$

$$F_6 = \frac{1}{6} \exp[(\theta_h - \theta_0) \tan \phi] \left\{ \sin(\theta_h - \theta_0) - \frac{L}{r_0} \sin \theta_h \right\} \\ \cdot \{ \exp(\theta_h - \theta_0) \tan \phi \sin \theta_h + \sin \theta_0 \}$$

The values of K as given in Eq.(1) are upper bound solutions for the yield acceleration factor corresponding to the log-spiral failure mechanism as shown in Fig. 2. Using the conditions

$$\frac{\partial F}{\partial \theta_0} = 0 \quad \text{and} \quad \frac{\partial F}{\partial \theta_h} = 0 \quad (2)$$

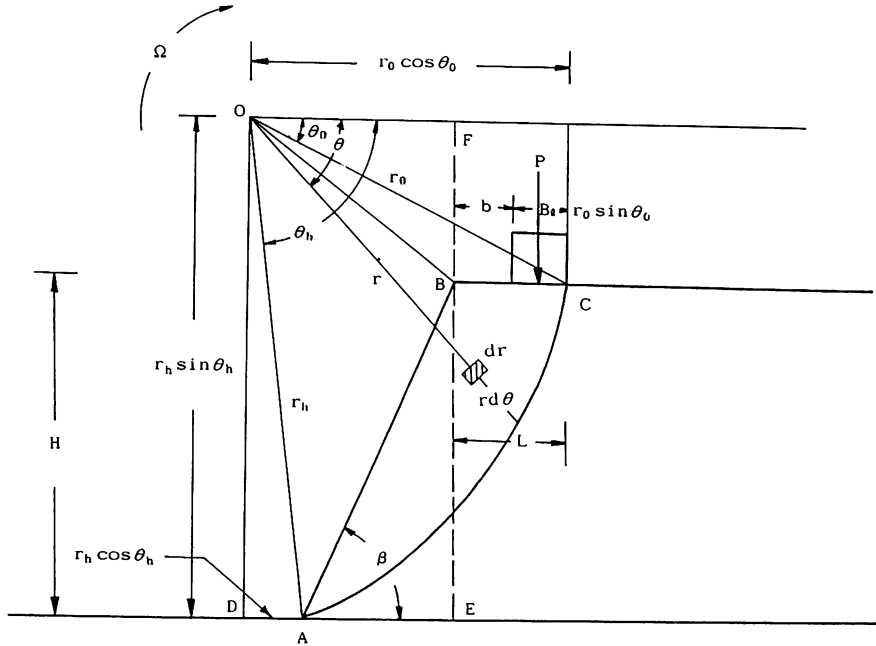


Fig. 2 Log-spiral failure mechanism

and solving Eq.(2), we obtain the critical values of θ_0 and θ_h which give the minimum value of K , or K_c as

$$K_c = \min. F(\theta_0, \theta_h) \quad (3)$$

The flow chart of computer program is shown in Fig. 3.

Extensive numerical results have been obtained by this program. Some of the results are illustrated graphically in Fig. 4–6.

Fig. 4 ... relation between K_c and slope angle(β)

Fig. 5 ... relation between K_c and internal friction angle(ϕ)

Fig. 6 ... relation between K_c and stability factor(N_s)

All results of log-failure mechanism less than the results of plane failure mechanism. So to speak, the log-spiral failure mechanism as shown in Fig. 2 should be taken as the local slope failure mode.

2. MODEL TEST

The soil as a material of the test is passed the sieve sized 25 mm, mixed a few silt and surface-dry condition. By mono-face shearing test and specific gravity test, we decided internal friction angle ϕ (36.03°), cohesion strength c (0.055 kg/cm^2) and specific gravity γ (2.64 g/cm^3). Using this material, we created the model slope in the box made from Acryl ($40\text{cm} \times 40\text{cm} \times 80\text{cm}$). As our understanding the behavior of seismic displacement and failure mechanism of a slope, we composed some stratum with line (about 5 cm between among the lines). (Photo. 1)

And a sample of acceleration record is presented in Fig. 7~8.

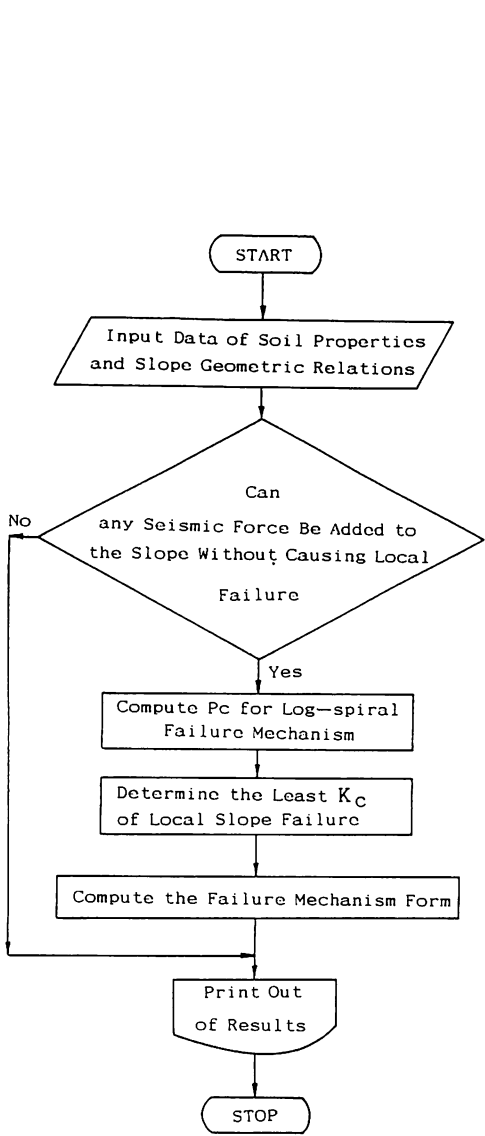


Fig. 3 Flow Chart of Computer Program

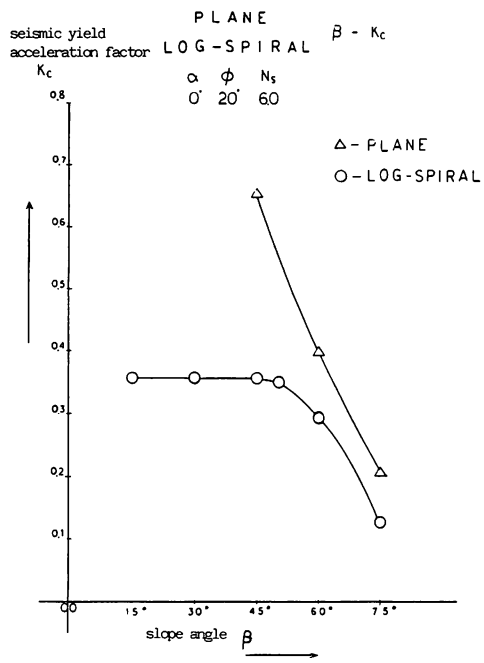


Fig. 4 Relation between K_c and Slope angle (β)

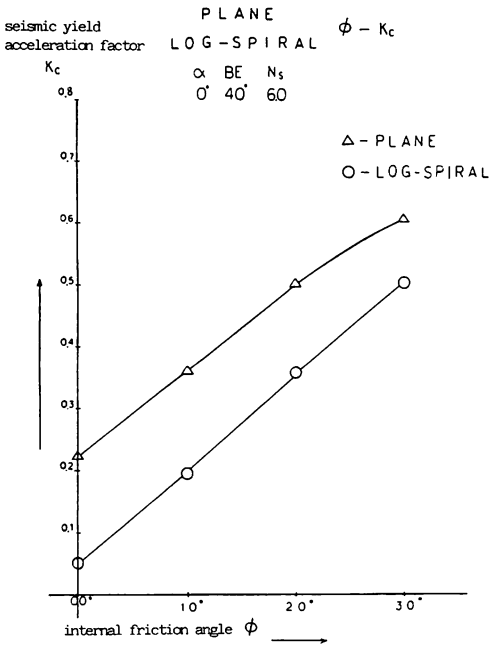


Fig. 5 Relation between K_c and internal friction angle (ϕ)

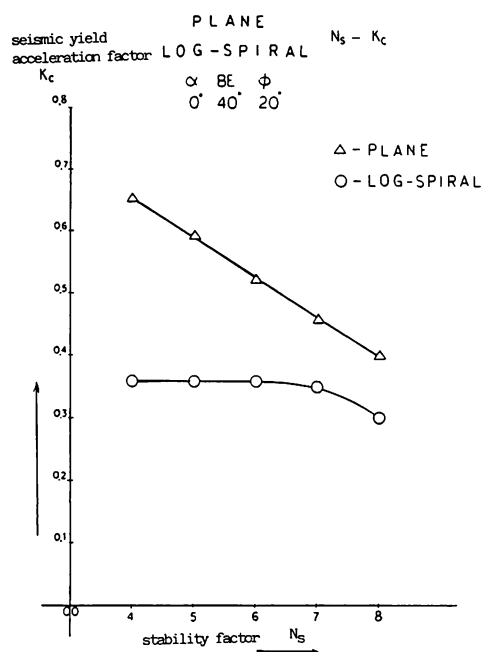


Fig. 6 Relation between K_c and Stability factor (N_s)

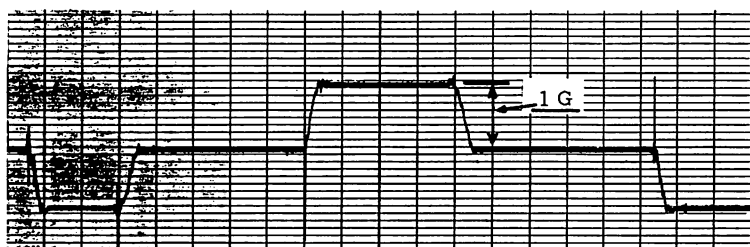


Fig. 7 Calibration

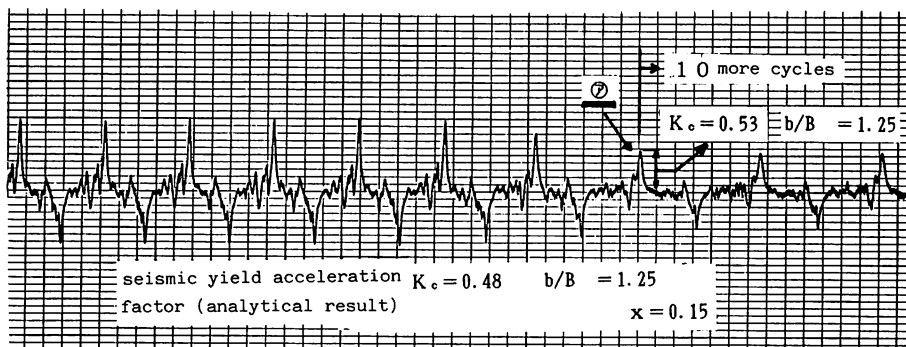


Fig. 8 Acceleration record - No. 1- (continue to No. 2)

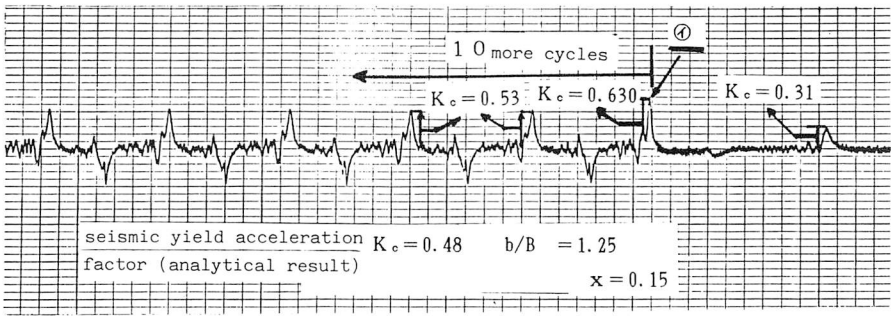


Fig. 8 Acceleration record -No. 2-

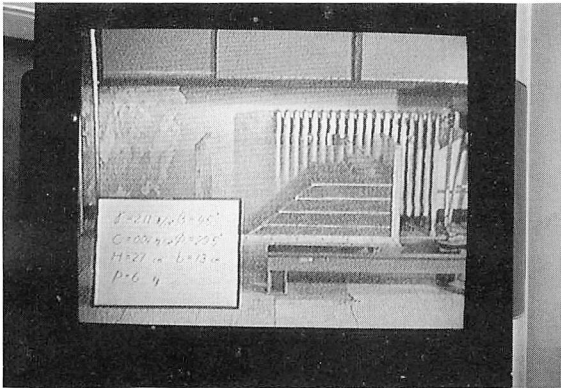
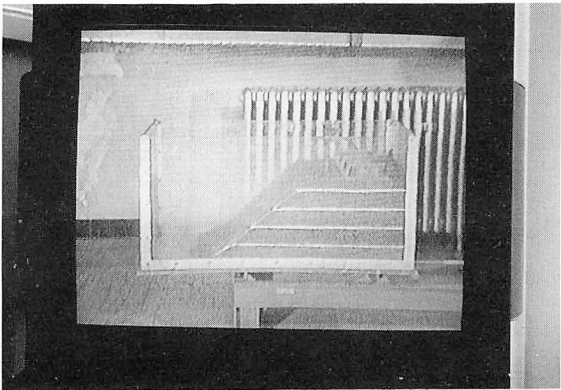
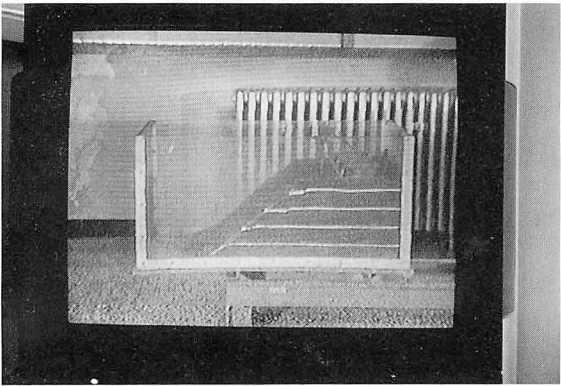


Photo. 1
Example 1 of Model Test

Express



Collapse
start just



Collapse start
right after

3. EFFECTS OF MODEL TEST INDUCED DYNAMIC WAVES

Photo. 2 shows a example of slope collapse of a model test.

In Table 1~4, it is shown that yield acceleration factors of effects of fifty-five test examples. As a result, in each table, Increasing the slope angle (β) and the slope height (h), slope tends to reduce stability. Also Table 3~4 show that length between the crown of the slope and the front of surcharge

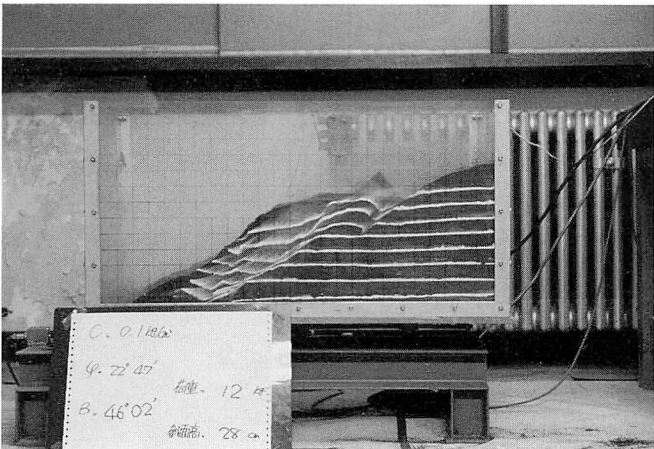


Photo. 2 A example of slope collapse of model tests

Effects of Model Experiments

tfble 1						table 2					
$\beta \backslash h$	20 cm	25 cm	30 cm	35 cm	Surcharger Condition	$\beta \backslash h$	20 cm	25 cm	30 cm	35 cm	Surcharger Condition
35 deg	0.452 G	0.416 G	0.405 G	0.400 G		35 deg	0.549 G	no failure			
45 deg	0.275 G	0.250 G	0.235 G	0.214 G		45 deg	0.296 G	0.292 G	0.242 G		
50 deg	0.240 G	0.222 G	0.213 G	0.203 G		50 deg	0.392 G	0.236 G	0.232 G	0.208 G	
60 deg	0.178 G	0.176 G	0.172 G	0.099 G		60 deg	0.214 G	0.210 G	0.210 G	0.202 G	
					P = 0 kg						P = 6 kg
					b = 0 cm						b=15 cm

Effects of Model Experiments

table 3						table 4					
$\beta \backslash h$	20 cm	25 cm	30 cm	35 cm	Surcharger Condition P = 6 kg b = 10 cm	$\beta \backslash h$	20 cm	25 cm	30 cm	35 cm	Surcharger Condition P = 6 kg b = 5cm
35 deg	no failure	no failure	0.497 G			35 deg	no failure	no failure	0.492 G	0.383 G	
45 deg	0.294 G	0.291 G	0.239 G	0.232 G		45 deg	0.240 G	0.226 G	0.199 G	0.180 G	
50 deg	0.282 G	0.220 G	0.208 G			50 deg	0.198 G	0.160 G	0.124		
60 deg	0.208 G	0.202 G	0.194 G			60 deg	0.128 G	0.120 G			

load (b) effects the seismic stability of slopes. In a word, As “b” decrease, slopes tend unsteady. The case of no surcharge load, being no compaction effect, the slope tends to reduce seismic stability rather than the case of surcharge condition. On the whole, these experiment-examples have almost good tendency.

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Appendix NOTATIONS

The following symbols are used in this paper ;

g : Acceleration of gravity.

γ : Gravity of soil per unit volume.

r_o : Radius of rotational failure mechanism. (in Fig. 2)

ϕ : Internal friction angle.

θ_o : Angle of starting point of failure mechanism. (in Fig. 2)

θ_h : Angle of ending point of failure mechanism. (in Fig. 2)

c : Cohesion strength.

l : Arm length of failure mechanism.

K : Acceleration factor of earthquake.

xK : Acceleration factor corresponding to P relating to K of soil weight multiplied by coefficient x , which can be greater or less than unity.

Ω : Angular velocity relative to the materials below the failure, surface about the center of rotation center ; O . (in Fig. 2)

L : Length of failure mechanism.

B_t : Length on surcharge load P .

b : Length from the crown to the end of surcharge load. (in Fig. 2)

P : surcharge load.

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